# West Burton Solar Project

# Environmental Statement Appendix 13.10: Heritage Viewpoint Methodology

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### Introduction

A photography and visualisation team was pulled together of leading photography and visualisation specialists from across the UK. Co-ordinated by Lanpro and led by Mike Spence of MSE. Mike brings over 30 years photography and visualisation experience, working on a wide range of complex infrstructure projects, fro major Highways schemes, to Carbon Capture, the power station development, tall buildings and solar projects across the UK.

Mike was a key technical authopr of the Landscape Institute's TGN 06/19 on visualisation of development proposals. He has worked alongside The National Trust, Historic England, English Heritage, RBG Kew, Historic Royal Palaces as well as NatureScot (formerly Scottish Natural Heritage) for whom he is currently working on updates to their windfarm visualisation guidance.

In 2021 Lanpro discussed the scope of the work with Mike Spence to develop a consistent strategy for technical photography and generation of highly accurate visualisations for major solar panel infrastructure. Initial work involved the calculation of the visibility of the solar panels, which were used to identify and agree viewpoints. In the winter of 2022 an initial 57 viewpoints were identified. Winter time photographs were taken between 20 March and 3 April 2022. An additional 15 viewpoints were identified and added in January 2023. All 72 had summer photography taken from the same locations between 8 July and 13 July 2022. An additional 4 viewpoints were added to the list for which only winter time photography was captured (Viewpoints 73 -76).

# **Verified Photography and 3D Modelling**

The photographs were taken with a full frame camera (Canon EOS 5D Mark IV) and 50mm lens combination consistent with Landscape Institute's TGN 06/19, GLVIA3 and the emerging understanding of the requirement for technical photography for visualisation work. As part of the work a total of 76 viewpoints were identified providing views of thedevelopment and visited for summer and winter photography in 2022 & 2023.

### Technical Photography

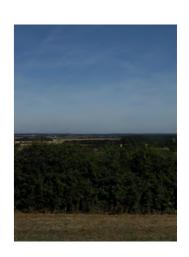
The camera was mounted on a Manfrotto 303 SPH panoramic tripod head, levelled using a Manfrotto Leveller, supported on a Manfrotto Tripod. The tripod head was levelled using a spirit level, to avoid pitch and roll. The camera was set with the centre of the lens



1.60m above ground level. Photographs were taken in Manual mode with an aperture of f/8 or f/11 and a fixed focal length throughout. Photographs were taken in landscape orientation. A Sigma 50mm f/1.4 lens was used for all viewpoint photographs. Two sets of equipment were used. The equipment was identical.



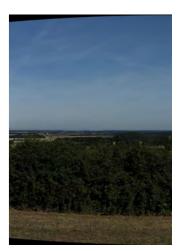




A Single Frame 50mm photograph is insufficient to capture the extents of a wide, linear development. Each view was taken with a series of overlapping 50mm images, as shown above.







To ensure consistent geometry each image was cylindrically re-projected, as above. This ensures that a full 360 degree panorama can be created to match the 3D model view, as shown below:



From the 360 degree panorama a 90 (or 180 degree) degree portion can be extracted to present the visualisations as shown below:



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### Surveying

The position of each camera location was surveyed using Spectra Precision GNSS equipment with Real Time Kinematic Correction (RTK) which achieves an accuracy down to 1cm in eastings, northings and height (metres Above Ordnance Datum). The equipment included Spectra Precision SP80 & SP85 GNSS smart antennae with Panasonic Toughpad data recorder. Points were saved using DigiTerra software. Photographs of the camera/tripod location were taken.



## 3D Modelling

MSEnvironmental (MSE) constructed a 3D model using the layout data supplied by Lanpro, OS MasterMap for geo-referencing and Environment Agency LIDAR DTM (2m). 3D point data was used for checking horizontal and vertical alignment.

For all viewpoints a 360 degree view was generated to capture the full extents of the development. This ensured that the full development would be present in the visualisations.

Camera locations surveyed on site were added to the geo-referenced 3D model.

Target points were taken from the existing features in the view and built into the 3D model. This allowed the horizontal and vertical alignment of the photograph and 3D model to be checked, cross-referenced and verified.

Cylindrical renders generated using VRay for Rhino were exported from the 3D modelling software and used to overlay the cylindrical images. Target points from both the photograph and the model view were aligned to ensure a precise fit between the two images.

Visualisations are presented as either AVR 0, 1, 2 or 3. The differences are explained in the Landscape Institute's Technical Guidance Note 06/19: Visualisation of Development Proposals.

The results are presented as a sequence of visualisations as follows:

### Existing Winter View



### Existing Summer View



3D Model View (Infrastructure)



AVR 3 Photomontage View (Year 1)



AVR3 Photomontage View (Year 15)



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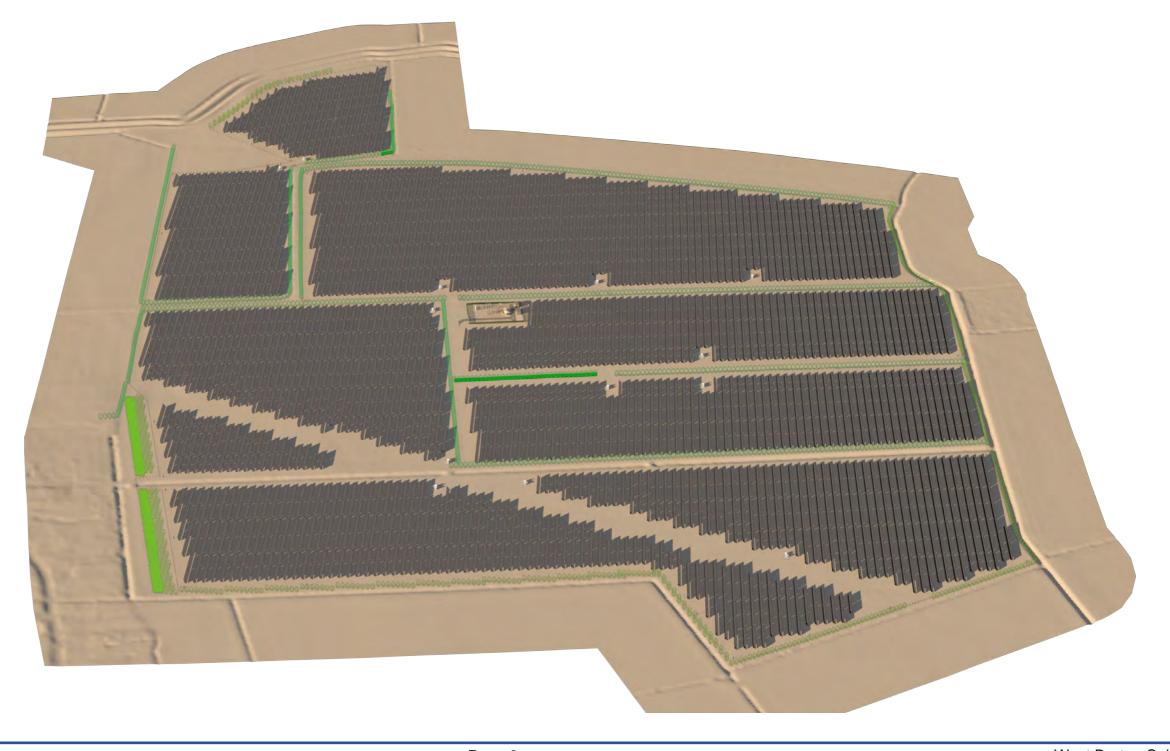
The topography of the site has been generated from Environment Agency LIDAR 2m DTM data, with triangulated surfaces generated using Rhinoterrain.

The model is fully geo-referenced and positioned to correspond with the site layout and elevations supplied in the engineering layouts. Landscaping has been added at two stages: Year 1 & 15. Heights have been specified by Landscape Architects at Lanpro.

West Burton 1 3D Model (Infrastructure & Year 15 Planting) on 2m LIDAR DTM data (OSGB36)

The resultant visualisations are considered to fairly demonstrate the correct scale and massing of the development.

Cameras have been added to the model and the field of view rendered out to precisely match the full 360 degree panoramic cylindrical images using highly precise camera co-ordinates.

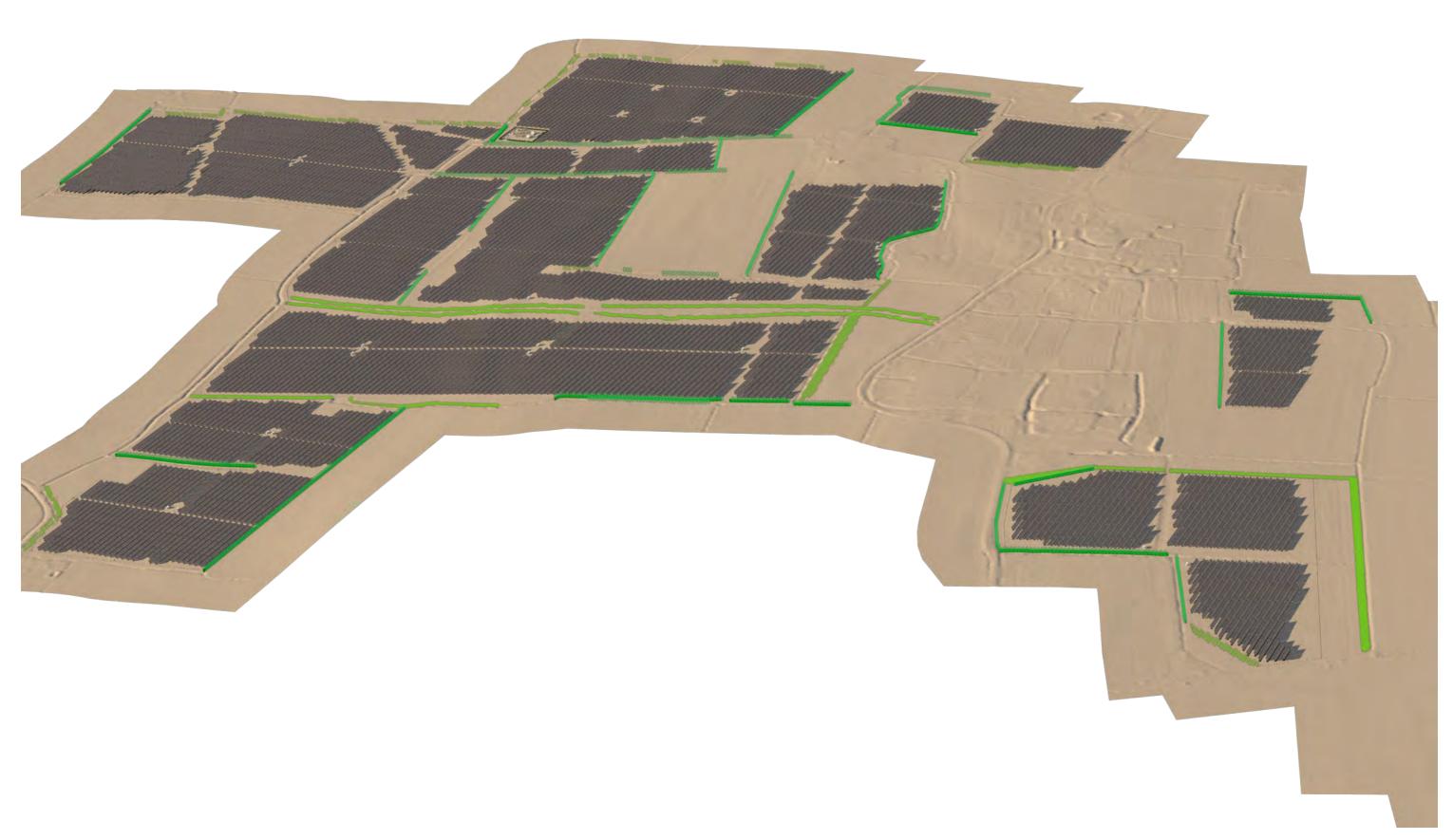








West Burton 2 3D Model (Infrastructure & Year 15 Planting) on 2m LIDAR DTM data (OSGB36)

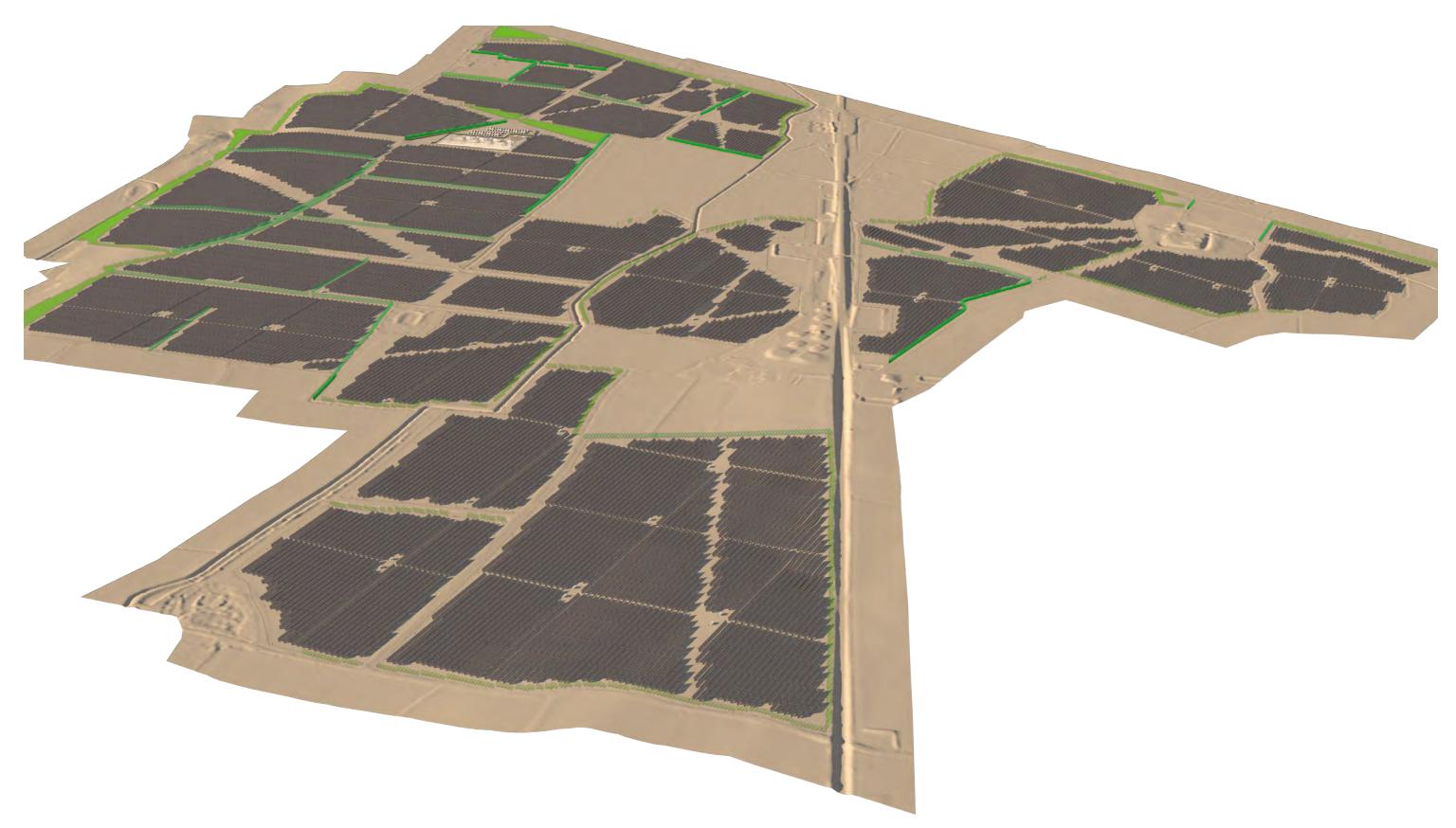








West Burton 3 3D Model (Infrastructure & Year 15 Planting) on 2m LIDAR DTM data (OSGB36)









### 50mm lens on Full Frame Sensor Camera

For decades it has been accepted that a 50mm lens on a full frame sensor camera provides the optimum image to replicate what is seen by the human eye. there are important differences between the human eye (binocular) and the camera lens (monocular). These have been explored in research by The Highland Council & the University of Stirling, as well as by myself through the Landscape Institute. We know that a single frame 50mm image on an A3 sheet of paper provides the same view as that gained in the field by someone with one eye closed. As we are binocular, and normally use both eyes, a different size of image is required, and the reason why we have presented the images as effectively a 75mm image on A2 paper. This gives what The Highland Council, University of Stirling, Scottish Natural Heritage (NatureScot) and the Landscape Institute agree is the most representative size of image to understand the nature and scale of a development on a photograph.

# **Planar or Cylindrical Projection**

All photographs are taken as single frame planar images. Each single frame image has a single point of perspective lying at the centre of the image. To correctly match and align with the 3D modelling software the camera must be mounted on a levelled tripod, and directed towards the proposed development.

When a viewpoint is close to the development, or a development is wide such as this solar farm, it is rarely possible to fit the development on a single frame image. The alternative is to use a series of overlapping 50mm images and generate a 'cylindrical' perspective view. This can be a full 360 degree wide panorama.

The 3D model renders have been rendered out in cylindrical (multiple frame images) projection to allow the precise image re-mapping to match the photography.

# 3D Modelling software

The work has largely been undertaken using Rhino 3D. All 3D modelling has been undertaken in metres and geo-referenced to align with OSGB36. RESOFT Windfarm was also used which is a 3D modelling package which we use to check on vertical and horizontal alignment of the 3D model against the precise image geometry. This is also set up to OSGB36. RESOFT Windfarm has been used to generate the geometric grid from LIDAR DTM data present in all 3D model visualisations.

# **Viewing Printed Images**

The visualisations have been prepared to be printed at A1 wide x A4 high (841 x 297mm) and in the this technical methodology document at A3 (420mm x 297mm), to fully show the original photographic imagery and scale of the proposed development.

The image size is considered to give a fair representation of the view for everyone, and the scale of the development in that view.

# **Summary**

This work has been undertaken in accordance with the Landscape Institute TGN 06/19 and the developing understanding of visualisation work. The accuracy of camera locations and 3D modelling conforms with the Landscape Institute's Type 4 (the highest level of accuracy). The 3D modelling has been produced to AVR 3 (photorealistic) and for some views AVR1 (simple dashed line identifying extents).

The photography has been undertaken in an extremely robust manner, using professional full frame sensor DSLR and 50mm lens with levelled tripod. The camera position has been surveyed using highly accurate GNSS equipment, giving high levels of accuracy of camera location. The 3D model has been built in Rhino 3D using detailed information supplied by the engineers aned a comprehensive landscaping scheme supplied by Lanpro. An additional check on the vertical scaling has been undertaken using RESOFT Windfarm.

The resultant visualisations are highly accurate.

The photography, surveying and 3D modelling have followed a transparent methodology, and the resultant visualisations and the size at which they are presented are considered robust and fit for purpose to illustrate the positioning, and scale and massing of the proposed scheme in its local and wider context.

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# **APPENDIX 1.1: VIEWPOINT SEQUENCES**

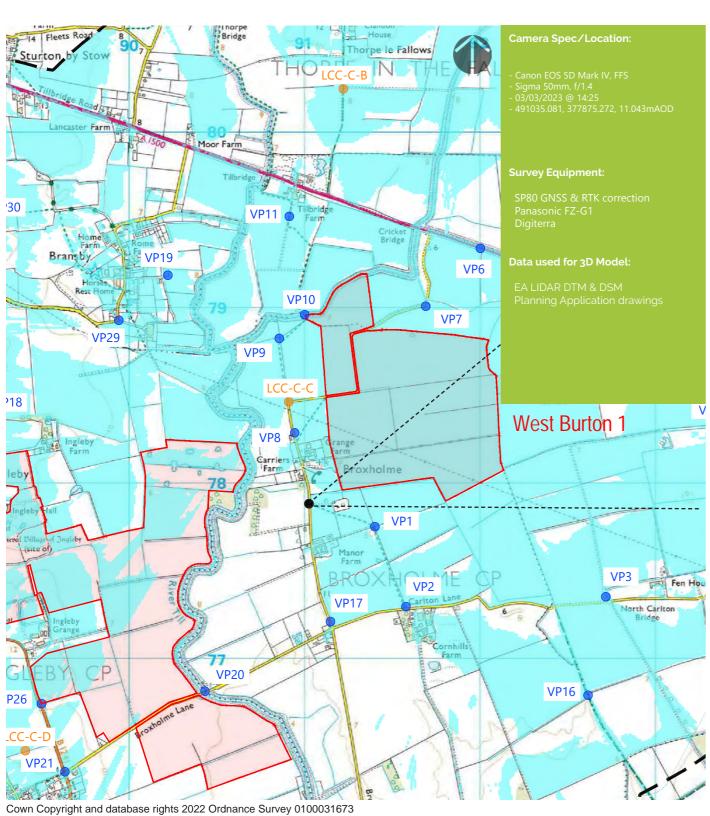






# **Heritage Viewpoint 1 (Winter)**

### **Camera Location:**



# Tripod:







Point of Perspective

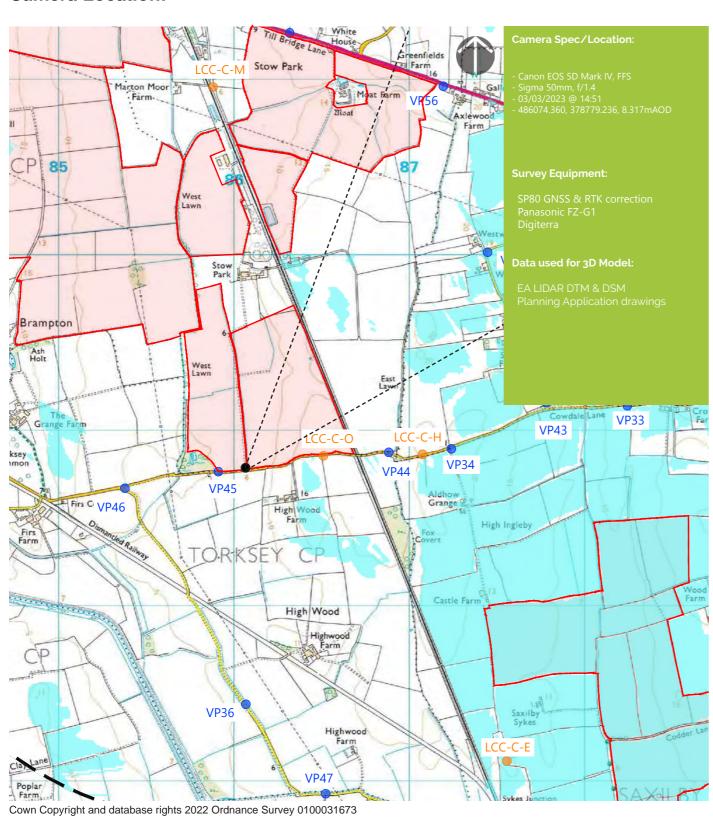






# **Heritage Viewpoint 2 (Winter)**

### **Camera Location:**



# Tripod:







Point of Perspective

Heritage Viewpoint 2 Single Frame 50mm image (Winter)

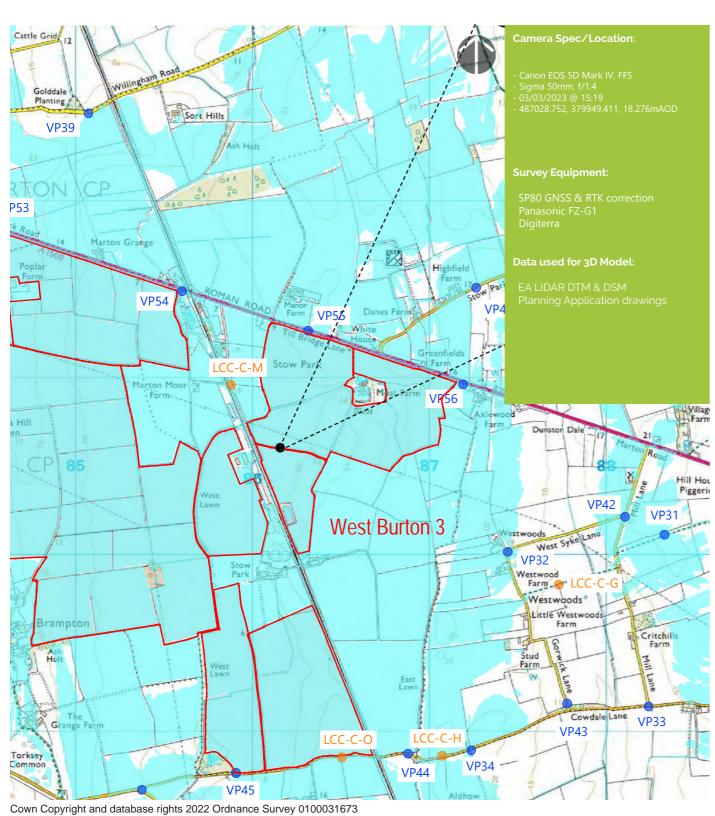






# **Heritage Viewpoint 3 (Winter)**

### **Camera Location:**



# Tripod:













# **Heritage Viewpoint 4 (Winter)**

### **Camera Location:**



# Tripod:



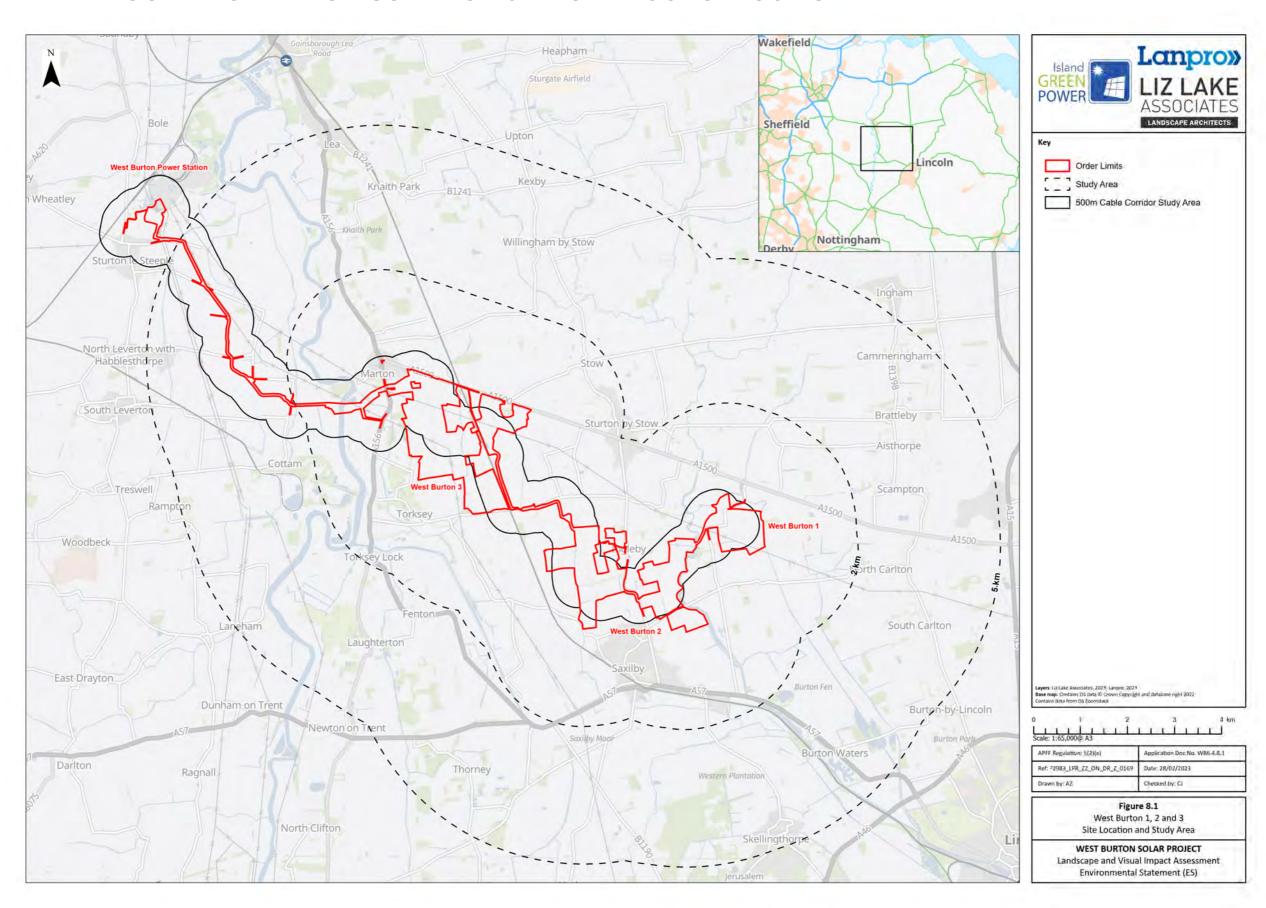








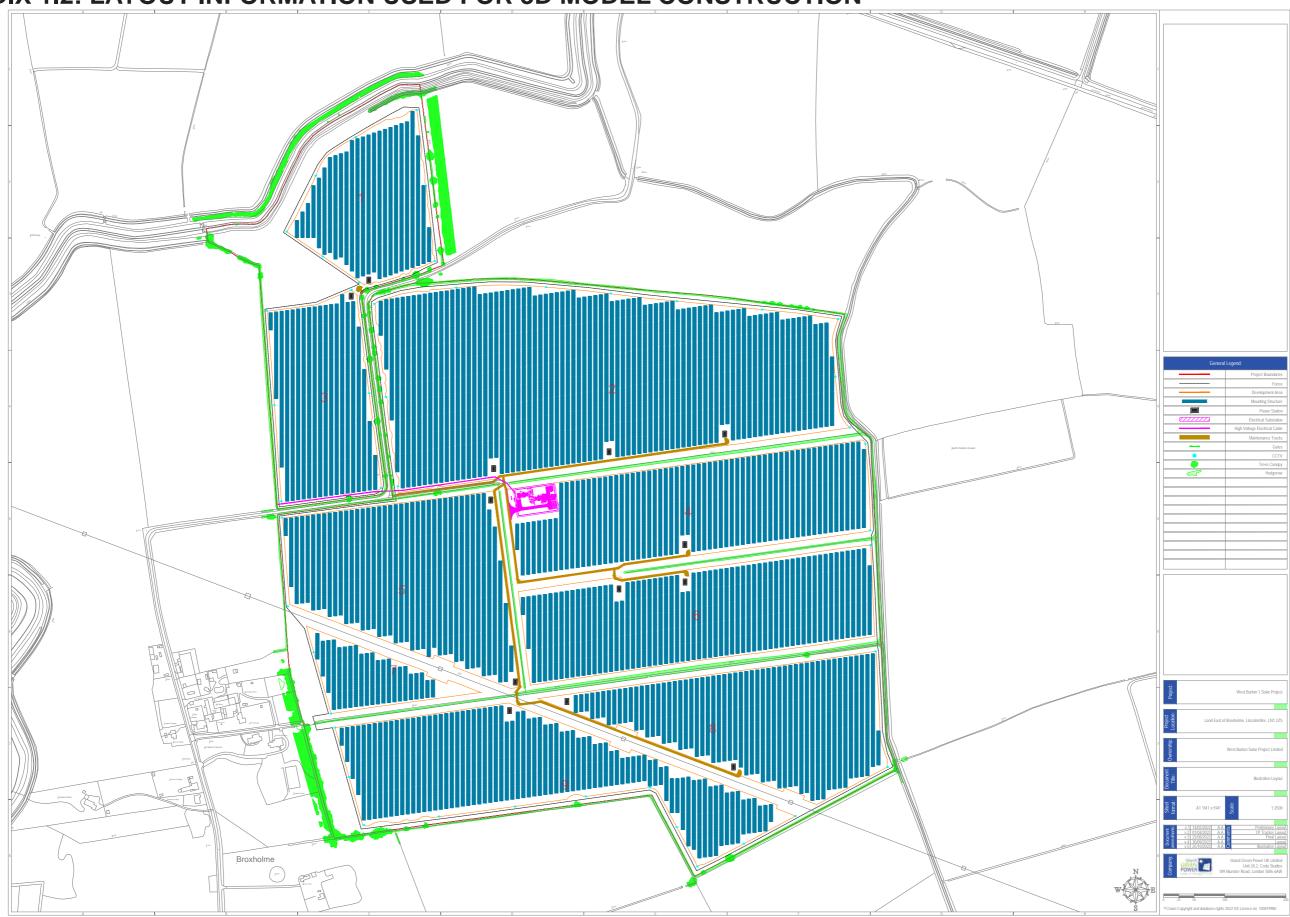








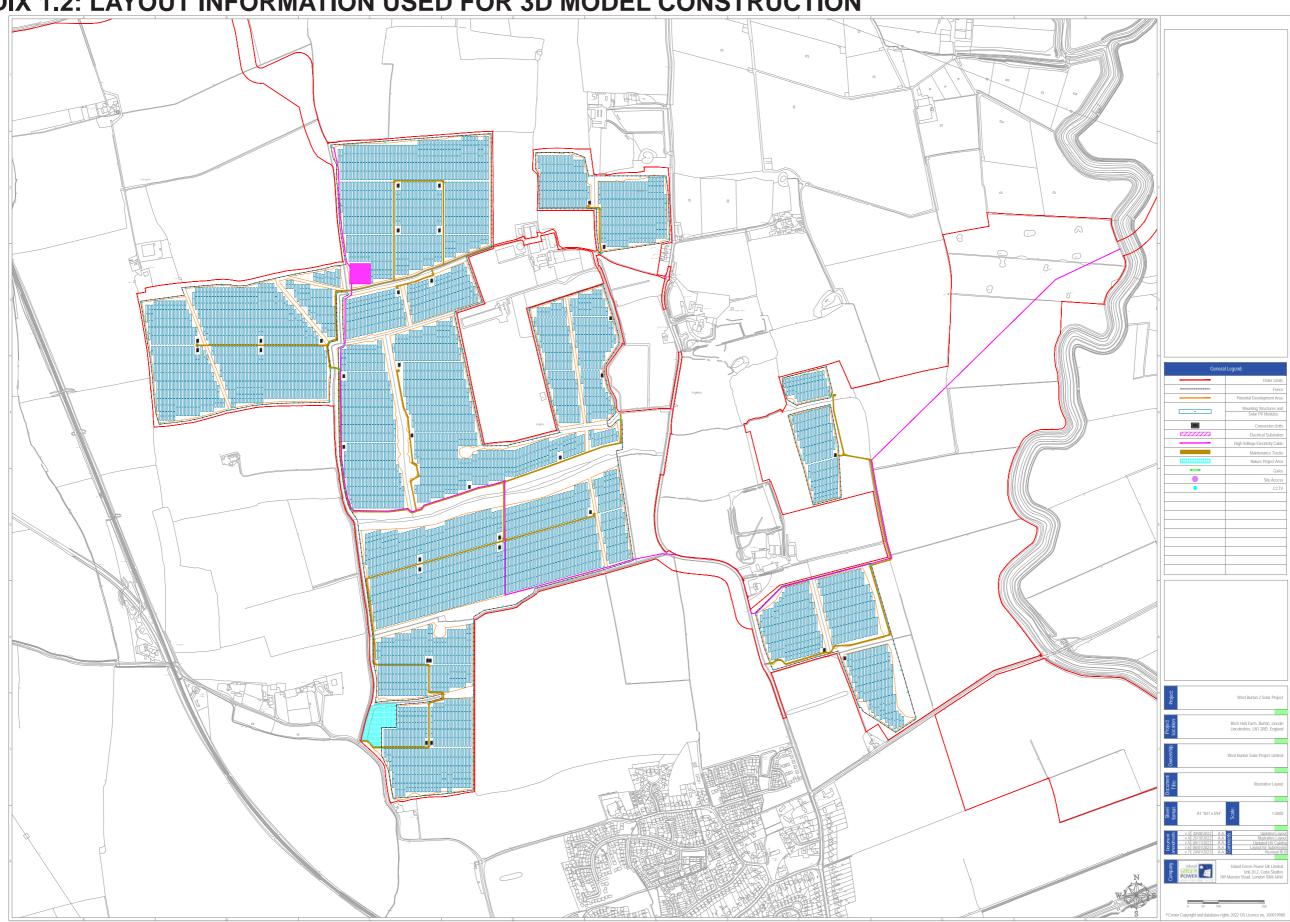








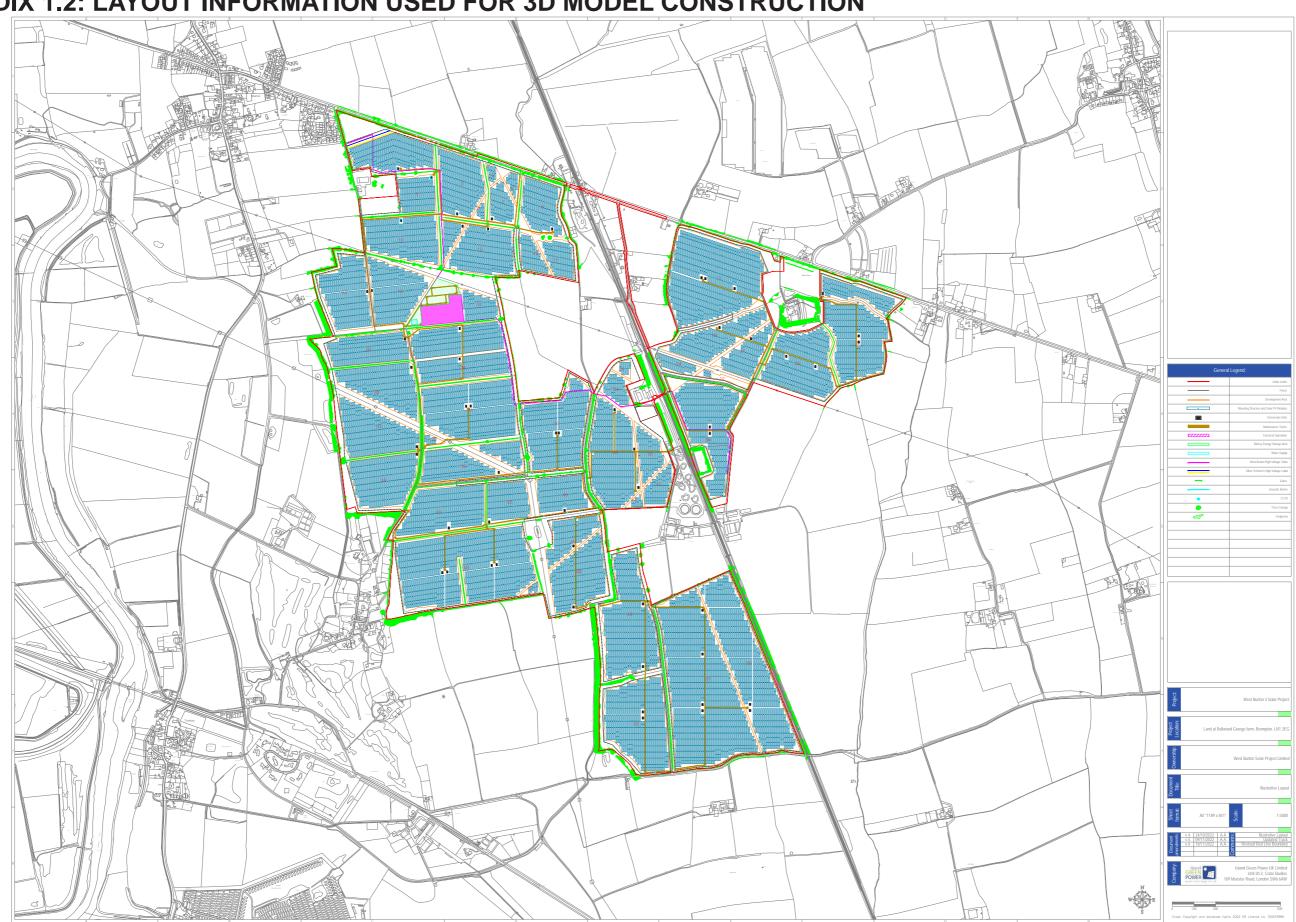




















# SFCO SINGLE-AXIS TRACKER TECHNICAL DATASHEET

### MAIN FEATURES

Tracking System Horizontal Single-Axis with independent rows Tracking Range up to ± 60° Enclosed Multidrive System, DC Motor **Drive System Power Supply** PV Series Self-powered Supply 2.0 Optional: 120/240 Vac or 24 Vdc power-cable Tracking Algorithm Soltec's TeamTrack™ with NREL SPA's astronomical data Communication Open Thread Full Wireless Optional: RS-485 Full Wired RS-485 cable not included in Soltec scope Wind Resistance Per Local Codes Land Use Features Independent Rows YES Slope North-South up to 17% Unlimited Slope East-West Ground Coverage Ratio Configurable. Typical range: 30-50% Driven Pile | Ground Screw | Concrete Foundation **Temperature Range** Standard - 4°F to +131°F | -20°C to +55°C Extended -40°F to +131°F | -40°C to +55°C Availability Modules Standard: 72 / 78 cells | Optional: 60 Cells; Crystalline,

### SERVICE PLANS

Pull Test
Factory Support
Onsite Advisory
Construction
Commissioning
Operation & Maintenance
Tracker Monitoring System
Solmate Customer Care

### MAINTENANCE

Self-lubricating Bearings
Face to Face Cleaning Mode
2x Wider Aisles
Fewer parts and fastenings

### WARRANTY

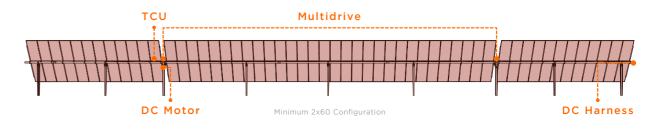
Structure 10 years (extendable) Motor 5 years (extendable) Electronics 5 years (extendable)

> B&V Bankability report DNV GL Technology Review available RWDI WIND TUNNEL TESTED

### MODULE CONFIGURATIONS Approximate Dimensions, scalable to bigger modules

2 x 5 6	Length 58.0 m (190' 5")	2 x 8 4	Length 87.1 m (286' 8")
2 x 5 8	Length 60.1 m (197' 2")	2 x 8 7	Length 90.1 m (296' 9")
2 x 6 0	Length 62.1 m (204' 10")	2 x 9 0	Length 93.2 m (306' 9")
	Height 4.1 m (13' 7")	Width 4.2 m	1 (13' 10")

Thin Film (Solar Frontier, First Solar and others)



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# **APPENDIX 1.3: SURVEY EQUIPMENT**









# SP80

### GNSS CHARACTERISTICS

- 240 DNSS channels
   GPS LICAL, LIPPLEC, LIPPL, LB
   GPS LICAL, LIPPLEC, LIPPL, LB
   GLONASS LICAL, LIP, LZCAL, LZP, LS
   Baldou (Phase II) Bl. B2
   Gallino FL ESE, ESB
   UZSS LICAL, LB, LIC, LZC, LB
   GBS LICAL, LB (WAAS, EGNOS, MSAS, GAGAN, SDCM)
   BNSS LS
   BNSS LICAL, LB (WAAS, EGNOS, MSAS, GAGAN, SDCM)
   BNSS LS
- IRNSS 1.5
   Support for Trimble RTX<sup>M</sup> real-time correction services
- Support for Human et Ar Treet ame contention services.
   Patented Z-Blade technology for optimal GNSS performance.
   Full utilization of signals from all 6 GNSS systems (GPS, GLONASS, Belfour, Gallier, OZSS and SRAS).
   Enhanced GNSS-centric algorithm: fully independent. GNSS signal tracking and optimal data processing including GPS-only, GLONASS-only or Belfour-only solution. [Actionomous to full RTIX].
- Fast Search engine for quick acquisition and re-acquisition of CNSS signals
- Perented SRAS ranging for using SRAS code & carrier observations and orbits in RTM processing
   Patented Strobe® Correlator for reduced GNSS multi-path
- . Up to 20 Hz real-time rew data (code & carrier and position
- output)
   Supported data formatis-ATOM, CHR, CMR+, RTCM 2.1, 2.2, 2.3, 3.0, 3.1 and 3.2 finefusing MSM2 CMRx and sCMRx (rover only)
   MHEA DIB3 messages output
- REAL-TIME ACCURACY (RMS) (RMS)

### Real-Time DGPS position

Horizontel: 25 cm + 1 p
 Vertical: 50 cm + 1 ppn

### Real-Time Kinematic Position (RTK)

Horizontal: 5 mm = 1 ppm
 Vertical: 15 mm = 1 ppm

# Network RTK(8) - Horizontal: 8 mm + 0.5 ppm - Vertical: 15 mm + 0.5 ppm

REAL-TIME PERFORMANCE
- Instant-HTM\* Initialization
- Typically 2-sec for baselines < 20 km
- Up to \$5.95 x reliability
- RTK Initialization range: over 40 km

### POST-PROCESSING ACCURACY (RMS) (802)

### Static & Fast Static

Horizontal: 3 mm = 0.5 ppm
 Vertical: 5 mm + 0.5 ppm

### High-Precision Static (3)

Horizontal: 5 mm + 0.1 ppm
 Vertical: 3.5 mm + 0.4 ppm

### DATA LOGGING CHARACTERISTICS

### Recording Interval • 0.05 - 999 seconds

PHYSICAL CHARACTERISTICS

### Size - 22.2 x 19.4 x 7.5 cm (8.7 x 7.6 x 3,0 in.)

### • 1,77 kg (2.57 m)

User Interface
- Graphical PMOLEU display
- WEB UI (accessible via WiEI) for easy configuration, operation, status, and data transfer

### VO Interface RS232 serial link

- USB 2.D/UART
   Bluetooth 2.1 EDR
- WiFt (802.1) h/g/n)
   . 3.93 quad-band GSM (850/900/1900/1900 MHz) / penta-band UHTS module (800/850/900/1900/200 MHz) Memory

  2 dB Internat memory NAMI Fleati
  (1.500 user data)
  Over a year of 15 sec. raw GNSS data
  from % satellites
  SD/SDMC internal memory card (up to 3200)

# Operation • RTK rover 8 base • RTK network rover: VPS, FKP, MAC • NTRIP, Direct IP

- · CSD mode
- Post-processing
   Post-processing
   RTK bridge
   OHF repeater
   UHF networking
   Trimble RTX(collular/iP)

# Environmental Characteristics Operating temporature: -40° to +85°C (-40° to +149°F)(\*)

- Storage temperature: -40° to +85°C (140° to +185°F) (1)
- Humidity: 10% condensing
  Humidity: 10% condensing
  Hip97 waterproof, sealed against sand and dust
  Orop: 2m pole drep on concrete
  Shock: ETSSO DOS
  Vibradion: MIL-STD-BIOP
  Power Characteristics
  All-Line Biot-Assessmble As tractor 35 6 bits

- rower Characteristics

   2.1-I-on hor-evappable betteries, 36.5 Wh
  (2 x 7.4 V, 2600 mAh)

   Battery Nils firm (two betteries), 10 hrz.
  (SNSS On, and GSM or WHF Px On)

   External DC powers 8-25 V

### At very low temperatures UH module should not be used in the transmitten mode.

- We make continue, particular can be stored up to a virtue.

   Notwark 81K PPN trailing have refer encoded to the closing blyscical base staking.

  Processes clinicalization turns varies bound on 4850 constraination beauthy lung for multipath, and presently to exist nuclear such as larger trees and faultings.

Acouracy and TEFF specifications may be affected by atmospheric conditions.

Signal multipath, satellite occur dily and supercentent was body and quality.

Performance valvius accuracy on more of the specifies, following the procedure performances or including individual formations, they find the party away, fresh PODE values and periods of source atmospheric conditions may disgrade.

Standard System Components

- SP60 receiver

- 2 L1-fen batteries

- Dual battery startor, power supply and international power corr kit

- Tape messure (3.6 m / 12 (1)

- T am pole extendatio

- USB to mini - USB table

- Hard case

- 2 year warrenty

Optional System Components

Optional System Components
- SP80 Utill Kit (410-478 MHz 2W 18x)
- SP80 Field Power Kit · SPSD Office Power Kit.

Normad 1050
 Field soitware
 Survey Pro
 FAST Survey
 Survey Mobile (Android)
 Shee control app for 3rd party
devices (Android)

· Data collectors - Ranger 3 - T41

- Nomad 1050

MobileMapper 50:

TRIMBLE RTX INITIALIZATION MENTO)

	Horizontal (RMS)	Initialization	GNSS
CENTERPOINT® RTX	<4 čm	<30 mire, <5 mire	11+12
***************************************			

CONTACT INFORMATION:

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Westminster CO BOUZI - USA -1-720-597-4700 Phone 888-477-7516 (Toll Free in USA) Europe, Middle East and Africa

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Please visit spectrageospatiaLcom for the latest product information and to locate your nearest distributor. Specifications and descriptions are subject to change without notice.

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# **APPENDIX 1.3: SURVEY EQUIPMENT**

# SP80 GNSS RECEIVER

The Spectra Geospatial SP80 is a next generation GNSS receiver that combines decades of GNSS RTK technology with revolutionary new GNSS processing. Featuring the new 240-channel "66" chipset combined with the patented Z-Blade technology, the SP80 system is optimized for tracking and processing signals from all GNSS constellations in challenging environments.

As the most connected GNSS receiver in the industry, the SP80 offers a unique combination of integrated 3.5G cellular, Wi-Fi and UHF communications with SMS, email and anti-theft technology.

These powerful capabilities, packaged in an ultra-rugged housing and patented antenna design with unlimited operation time (hot-swappable batteries), make SP80 an extremely versatile turnkey solution.







### **KEY FEATURES**

- · Patented Z-Blade technology
- · 240-channel 6G ASIC
- Hot-swappable batteries
   Internal TRx UHF radio
- Thermal FRX OHF radio
   3.5G cellular modem
- Built-in WiFi communication
- SMS and e-mail alerts
- Anti-theft technology
- Backup RTK
   RTK Bridge
- eLevel technology
- eLevel technology
- Trimble RTX correction services









### UNIQUE 8G GNSS-CENTRIC TECHNOLOGY

Patented Z-Blade processing technology running on a next generation Spectra Geospatial 240-channel 66 ASIC fully utilizes all 6 GNSS systems: GPS, GLONASS, BeiDou, Galileo, QZSS and SBAS. Unlike GPS-centric technology which requires a minimum number of GPS satellites for GNSS processing, Z-Blades unique GNSS-centric capability optimally combines GNSS signals without dependency on any specific GNSS system; this allows SP80 to operate in GPS-only, GLONASS-only or BeiDou-only mode if needed. In addition, SP80 supports the recently approved RTCM 3.2 Multiple Signal Messages (MSM), a standardized definition for broadcasting all GNSS signals from space, regardless of their constellation. This protects the surveyor's investment well into the future by providing superior performance and improved productivity as new signals become available.

### SMS AND EMAIL MESSAGING

SP80 has a unique combination of communication technologies including an integrated 3.56 GSM/UMTS modem, Bluetooth and Wi-Fi connectivity, and optional internal UHF transmit radio. The cellular modem may be used for SMS (text message) and e-mail alerts as well as regular Internet or VRS connectivity. SMS (text messages) can be used to monitor and configure the receiver. Likewise, SP80 can use all available RTK correction sources and connect to the Internet from the field using WiFi hotspots, where available. The internal UHF transmit/receive radio allows for quick and easy setup as a local base station. This saves time and increases the surveyor's efficiency.

### ANTI-THEFT PROTECTION

A unique anti-theft technology secures SP80 when installed as a field base station in remote or public places and can detect if the product is disturbed, moved or stolen. This technology allows the surveyor to lock the device to a specific location and make it unusable if the device is moved elsewhere. In this case, SP80 will generate an audio alert and show an alert message on its display. Furthermore, a SMS or e-mail will be sent to the surveyor's mobile phone or computer and provides the receiver's current coordinates allowing tracking of its position and facilitating recovery of the receiver. SP80's anti-theft technology provides surveyors with remote security and peace of mind.

### TRIMBLE RTX CAPABLE

Trimble RTX correction services offer a wide range of accuracy requirements ranging from better than 4 cm accuracies, up to sub-meter accuracies, without the need of an RTK base station.

Trimble RTX is available for the SP80 GNSS receiver via cellular/IP delivery. The premium service, CenterPoint® RTX is the most accurate satellite-delivered correction service available today. With the SP80 GNSS receiver and a Trimble RTX correction, achieve high-accuracy positioning nearly anywhere in the world.

### THE MOST POWERFUL TOOL FOR RELIABLE FIELD USE

The SP80's rugged housing, created by Spectra Geospatial's engineering design lab in Germany, incorporates a host of practical innovations. Dual hot-swappable batteries can be easily exchanged in the field as a one hand operation for an interruption-free working day, ensuring surveyors remain productive until the job is done. The impact-resistant glass-fiber reinforced casing, designed to withstand 2m pole drops and waterproof to IP67, ensures that SP80 can handle the toughest outdoor conditions. The patented UHF antenna, set inside the rugged carbon fiber rod, extends the range of RTK radio performance at the same time as armoring protection. The sunlight-readable display offers instant access to key information like the number of satellites, RTK status, battery charge and available memory. With eLevel technology, the user is able to focus in one place when leveling and measuring as well as automatically store measurements when the receiver is level. These powerful design features combine to make SP80 the most capable, most reliable GNSS receiver, backed by a comprehensive standard 2 year warranty.



### THE SPECTRA GEOSPATIAL EXPERIENCE

With the most advanced and rugged field data collectors from Spectra Geospatial, surveyors get maximum productivity and reliability every day. Spectra Geospatial Survey Pro or FAST Survey software is specifically tailored for the SP80 GNSS receiver providing easy-to-use, yet powerful GNSS workflows, letting the surveyor concentrate on getting the job done. Spectra Geospatial Survey Office Software provides a complete office suite for post-processing GNSS data and adjusting survey data, as well as exporting the processed results directly back to the field or to engineering design software packages. Combined with Spectra Geospatial field and office software, SP80 is a very powerful and complete solution.



# Lanpro GREEN POWER



# **APPENDIX 1.3: SURVEY EQUIPMENT**

# TOUGHPAD FZ-G1

### Panasonic recommends Windows.

SOFTWARE	<ul> <li>Windows 10 Pro 64 bit</li> <li>Panasonic Utilities [including Dashboard], Recovery Partition</li> </ul>	
DURABILITY	MIL-STD-810G certified (4' drop, shock, vibration, rain, dust, sand, altitude, freeze/thaw, high/low temperature, temperature shock, humidily, explosive atmosphere! PAS certified sealed alt-weather design Optional class I division 2, groups ABCD certified mode! Solid state drive heater Magnesium altoy chassis encased with ABS and elastomer corner guards Optional hand strap or rotating hand strap Port covers Raised bezel for LCD impact protection Pre-installed replaceable screen film for LCD protection	
СРИ	■ Intel <sup>®</sup> Core <sup>™</sup> i5-6300U vPro <sup>™</sup> Processor - 2.4 GHz up to 3.0 GHz with Intel <sup>®</sup> Turbo Boost Technology - Intel Smart Cache 3MB	
STORAGE & MEMORY	86B DDR3L SDRAM <sup>LS</sup> 256GB solid state drive (SSD) with heater <sup>LS</sup> Optional 512GB     up to 64GB additional storage with optional microSDXC card slot	
DISPLAY	10.1" WUXGA 1920 x 1200 with LED backlighting 10-point capacitive multi touch + Waterproof Digitizer pen daylight-readable screen - 2-800 nit - IPS display with direct bonding - Anti-reflective and anti-glare screen treatments - Ambient light sensor, digital compass, gyro and acceleration sensors - Automatic screen rotation - Intel® HD Graphics 520 [Bult-in CPU] video controller - Conceleded mode (configurable)	
AUDIO	Integrated microphone     Realtek high-definition audio     Integrated speaker     On-screen and button volume and mute controls	
KEYBOARD & INPUT	10-point gloved multi touch + digitizer screen - Supports bare-hand touch and gestures and electronic waterproof stylus pen - Supports glove mode and wet-touch mode 1 table buttons (2 user-definable) Integrated stylus holder 0 n-screen QWERTY keyboard	
CAMERAS	720p webcam with mic 8MP rear camera with autofocus and LED light	
EXPANSION	Optional MicroSDXC3	
INTERFACE	■ Docking connector 24-pin Type A HDMI 14-pin 14-p	
WIRELESS	Quitonal integrated 4G LTE multi carrier mobile broadband with satellite GPS  Optional GPS (u-blox NEO M8N) <sup>2</sup> Intel® Dual Band Wireless-AC 6260 [IEEE802.11a/b/g/n/ac] Bluetooth 4.1, Classes mode/ Low Energy mode, Class I [Windows 10 pro 64-bit]  Security - Authentication: LEAP, WPA, 802.1x, EAP-TLS, EAP-FAST, PEAP - Encryption: CKIP, TKIP, 128-bit and 64-bit WEP, Hardware AES  Bual high-gain antenna pass-through	
POWER SUPPLY	Li-lon battery pack:  - Standard battery: Li-ion 11.1 V, 4200 mAh [typ.], 4080 mAh [min.]  - Optional long life battery': Li-ion 10.8V, 9300mAh[typ.], 8700mAh [min.]  Battery operation':  - Standard battery: 14 hours  - Optional long life battery': 28 hours  Battery charging time':  - Standard battery: 25 hours off, 3 hours on  - Optional long life battery': 3 hours off, 4 hours on  - Optional long life battery': 1 minute ways time]	
POWER MANAGEMENT	■ Suspend/Resume Function, Hibernation, Standby	
SECURITY FEATURES	Password Security: Supervisor, User, Hard Disk Lock  Kensington cable lock slot Trusted platform module [TPM] security chip v2.012 Computrace* that protection agent in BIOS8 Optional Insertable SmartCard reader <sup>27</sup>	

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RRANTY year limited warranty, parts and labor
ENSIONS & WEIGHT <sup>9</sup>
0.6"(L) x 7.4"(W) x 0.8"(H)
4 lbs. (standard battery)

INTEGRATED OPTIONS<sup>18</sup>

4 G LTE mutil carrier mobile broadband with satellite GPS

Choice of 10/2D barcode reader [EA1 or EA21], GPS, Serial Dongle, Ethernet, MicroSDXC or second USB 2 ID port<sup>1</sup>

Choice of bridge battery, magstripe reader, insertable SmartCard reader, insertable SmartCard reader with bridge battery, contactless SmartCard/RFID HF reader or UHF 900MHz RFID reader [EPC Gen 2]<sup>227</sup>

A (	CLESCUBIES	10
A		
_	AC Ad4 [	2

1	AC Adapter (3-prong)	CF-AA6413CM
i	Standard Battery Pack	FZ-VZSU84A2U
	Long Life Battery Pack <sup>7</sup>	FZ-VZSU88U
	Long Life Battery Bundle	
	(includes rotating hand strap and corner guard set)	FZ-BNDLG1LL1ST1
	Single Battery Charger Bundle	FZ-BNDLG1BATCH
	LIND 3-Bay Battery Charger	FZ-LND3BAYG1
	LIND Car Adapter 120W	CF-LNDDC120
	LIND Car/AC Adapter 90W (with USB port)	CF-LNDACDC90
	LIND Car Adapter 90W MIL-STD	CF-LNDMLDC90
	Tall Corner Guard Set	FZ-WCGG111
	Rotating Hand Strap and Tall Corner Guard	
	Set Bundle	FZ-BNDLG1ST1CG4
	ToughMate G1 Always-On Case (with hand strap)	TBCG1AONL-P
	ToughMate G1 Professional Portfolio	TBCG1PFLIO-BLK-
	ToughMate G1 "X" Hand Strap	TBCG1XSTP-P
	Desktop Cradle	FZ-VEBG11AU
1	Vehicle Docks (no pass-through)	

















# APPENDIX 1.4: CAMERA EQUIPMENT (CANON 5D MARK IV)









# **APPENDIX 1.4: CAMERA EQUIPMENT (SIGMA 50mm f/1.4)**







Incredible resolution ideal for the high-megapixel era. Introducing the new benchmark large-aperture standard lens

In 2008, Sigma released a large diameter standard lens designed for digital SLRs, "SIGMA 50mm F1.4 EX DG HSM". At that time, products for film cameras were prevalent, yet we spent enormous effort to set a new benchmark for the 50mm lens that optimizes the characteristics of digital cameras, such as compensating peripheral brightness, controlling the point images in the corners, and improving the image drawing, not only around the focusing point, but also other areas in the image.



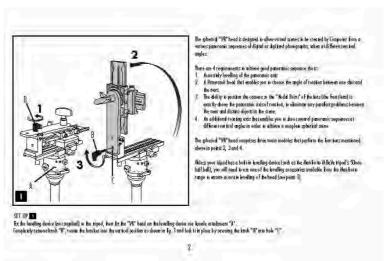


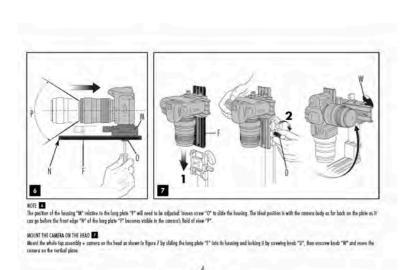


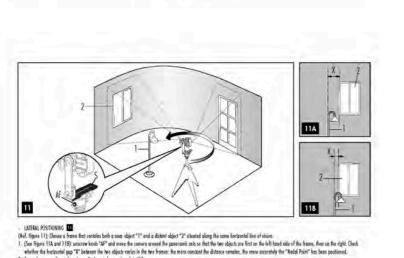
# **APPENDIX 1.4: CAMERA EQUIPMENT (MANFROTTO 303 SPH)**





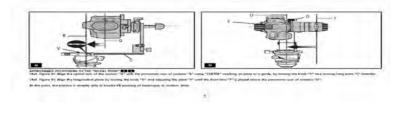


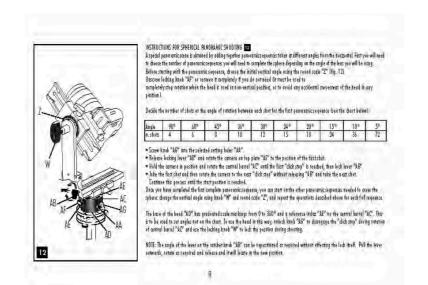


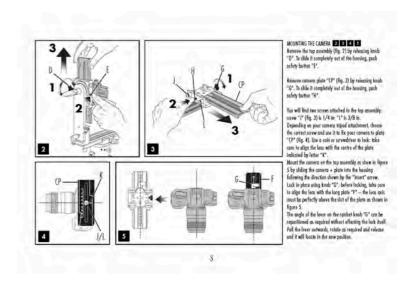


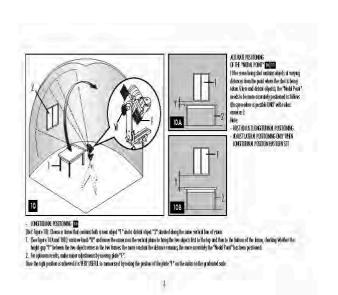
2: For optimum results, make miner adjustments by moving plate "S".

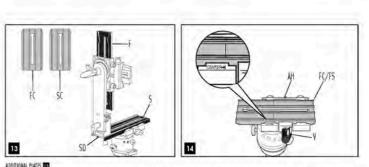
Once the right position is achieved it is VERY USEFUL to memorise it by nating the position of the plate "5" on the index on the graduated scale.











ADDITIONAL PLATES IS If you have you compact comerce we suggest you by a weight of the exystem.

To replace the plate "5" inscrew screw "50" (fig. 13)

To replace the plate "E", please refer to fig. 6 and inscr omera we suggest you to one the short plates "X." (fig. 13) and "K." (sugglied with the head) finited of the two lone plates "F" and "S" in order to reduce some and

USE OF THE RIT AS AN OBJECT PARIORANA TURNISHE TO
The head one also be used on a furnishing until for shorting object ponoromics. For this use, fusion knob "V" and puch button "AH" to slide the lower plate "S" out of the booking on the ponoromic rotation bose until in place of the long plate and top assembly, around one of the less storpler plates supplied as a base for your abject. The plate heasing has a "tenter" mark to thelp you position your object accurately above the center of panoromic rotation.